

Notes

CHROM. 4000

Computer program for calculation of gradients for column chromatographic elution

Linear elution gradients are useful in many of the applications of column chromatography¹ but more complex patterns of salt or pH alteration during elution are sometimes helpful in achieving specific separations. Reliable devices have been described for the formation of such gradients² and it is a simple matter to calculate the gradient that will be produced by such a device when specified concentrations

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PROGRAM GRACAL C (INPUT, OUTPUT, TAPES = INPUT, TAPE6 = OUTPUT)
C READ DESIRED GRADIENT AT 100 PERCENTAGE POINTS (COUT)
DIMENSION COUT(100), CIN(9), CONT(9,100), C(100), DEV(100),
10SQ(100), FRAC(9,100), AVCOR(9), PER(100), A(100,3)
DATA SDSQ1/0.07
DECR = 1000.
100 READ (5,200) COUT
200 FORMAT (10(F8,3))
GO TO 250
225 DECR=0.5*DECR
250 CONTINUE
C MAKE INITIAL ESTIMATES OF CHAMBER CONCENTRATIONS, CIN
CIN(1)=COUT(1)
CIN(2)=COUT(12)
CIN(3)=COUT(24)
CIN(4)=COUT(37)
CIN(5)=COUT(50)
CIN(6)=COUT(61)
CIN(7)=COUT(74)
CIN(8)=COUT(86)
CIN(9)=COUT(100)
C COMPUTE LATEST GRADIENT, C
I=0
300 DO 400 J=1,100
A=(FLOAT(J))/100.
CONT(1,J)=CIN(1)*((1.-A)**8)
CONT(2,J)=CIN(2)*8.*((1.-A)**7)*(A)
CONT(3,J)=CIN(3)*28.*((1.-A)**6)*(A)**2
CONT(4,J)=CIN(4)*56.*((1.-A)**5)*(A)**3
CONT(5,J)=CIN(5)*70.*((1.-A)**4)*(A)**4
CONT(6,J)=CIN(6)*56.*((1.-A)**3)*(A)**5
CONT(7,J)=CIN(7)*28.*((1.-A)**2)*(A)**6
CONT(8,J)=CIN(8)*8.*((1.-A)**1)*(A)**7
CONT(9,J)=CIN(9)*((A)**8)
400 CONTINUE
DO 500 J=1,100
C(J)=0.
500 CONTINUE
DO 550 J=1,100
DO 550 K=1,9
C(J)=C(J)+CONT(K,J)
550 CONTINUE
C COMPUTE DIFFERENCES AND TEST THEM
DO 600 J=1,100
DFV(J)=C(J)-COUT(J)

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Fig. 1. Part one of the gradient calculation program.

of eluant are placed in the mixer, using either general formulas² or nomograms designed for the purpose³. It is rather more tedious to calculate the concentrations of eluant that must be placed in the mixer to give a specified gradient, and a process of successive approximations from tables of calculated partial values has been suggested as satisfactory for most purposes². This paper gives a program for the calculation of mixer concentrations which will give a good fit to a specified gradient under prescribed experimental conditions. The program can be used with the computer facilities that are now readily available to most investigators.

Method of calculation

The program is written in Fortran IV and has been used on a Control Data Corporation Model 6400 Computer System at the University of Colorado Computer Center. The commercially available gradient mixing devices are customarily nine-chambered and the program is designed specifically for such an apparatus although it could readily be modified to accommodate a larger or smaller number of chambers by altering the appropriate indices in the calculation. The user specifies the desired

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600 CONTINUE
SMD=0.
DO 800 J=1.100
SMD=SMD+DEV(J)
800 CONTINUE
IF (SMD.GT.1.E+90) GO TO 225
DO 801 J=1.100
DSQ(J)=0.
801 CONTINUE
DO 8011 J=1.100
DSQ(J)=DEV(J)**2
8011 CONTINUE
SDSQ=0.
DO 802 J=1.100
SDSQ=SDSQ+DSQ(J)
802 CONTINUE
IF (SDSQ.LT.1.E-04) GO TO 8980
T=1.
IF (T.GT.35.AND.SDSQ.GT.SDSQ1) GO TO 8920
SDSQ1=SDSQ
IF (T.GE.999) GO TO 8900
DO 820 K=1.9
DO 820 L=1.100
FRAC(K,L)=0.
820 CONTINUE
DO 900 K=1.9
DO 900 L=1.100
IF (DEV(L)) 822,822,824
822 SIGN=1.
GO TO 826
824 SIGN=-1.
826 FRAC(K,L)=CONT(K,L)*SIGN*DSQ(L)/C(L)
900 CONTINUE
DO 910 K=1.9
AVCOR(K)=0.
910 CONTINUE
DO 1000 K=1.9
KK=(12*K)-11
DO 1000 L=1.KK
B=FLOAT(KK)
AVCOR(K)=(AVCOR(K)+FRAC(K,L))/B
CIN(K)=CIN(K)+DECR*AVCOR(K)

```

Fig. 2. Part two of the gradient calculation program.

shape of the gradient in terms of molar concentrations at 100 equally spaced points along the gradient. The program then calculates by successive approximations the concentrations of eluant to be placed in the mixing chamber to give the desired gradient. The resulting input concentrations and the calculated mixer output are tabulated numerically, along with the percentage deviation of each calculated point from the corresponding input datum. In order to estimate quickly the adequacy of the correspondence between the calculated and the desired gradient, a standard printer plot subroutine is then instructed to display the results of the calculation⁴.

In the programming no attempt was made to condense maximally the computer instructions with respect either to machine space or computing time, because the extended version will probably be more readily modified by future users to meet special conditions. The approximation method used is one of successive bisection of the error at each iteration of the calculation and was selected in order to avoid difficulties with conditional convergences⁵. The relatively slow convergence of such a method is no disadvantage with modern high speed computing machines. The program is arranged to stop when the agreement between the desired and calculated gradients becomes better than a specified error (which may readily be altered by the user), or to stop if the approximation process ceases to converge, or to stop after a specified number of iterations (999 as written but simply adjustable by the user). The final result of the calculation is tabulated and plotted graphically for inspection in all cases.

```

1000 CONTINUE
      GO TO 300
8900 WRITE (6,8910) I
8910 FORMAT (1H1,134HSTANDARD TOLERANCE EXCEEDED AFTER .13.1X.10HITERAT
      IONS)
8920 WRITE (6,8930) I
8930 FORMAT (1H1,137HAPPROXIMATION PROCESS DIVERGES AFTER .13.1X.10HITE
      RATIONS)
      GO TO 9000
8980 WRITE (6,8990) I
8990 FORMAT (1H1,137HFITTED WITHIN STANDARD TOLERANCE IN .13.1X.10HITERA
      TIONS)
9000 DO 9100 J=1,100
      PER(J)=(DEV(J)/COUT(J))*100.
9100 CONTINUE
      WRITE (6,9200)
9200 FORMAT (1H0, 32H          CHAMBER    MOLARITY//)
      WRITE (6,9300) (K, CIN(K), K=1,5)
9300 FORMAT (15X,13.8X,F6.4)
      WRITE (6,9400)
9400 FORMAT (1H0,66H          FRACTION    SPECIFIED    CALCULATED    PER
      CENT DEVIATION//)
      WRITE (6,9500) (L,COUT(L),C(L),PER(L),L=1,100)
9500 FORMAT (8X,13.9X,F6.4, 6X,F6.4,16X,F6.2)
      DO 9600 L=1,100
      A(L,1)=L
      A(L,2)=COUT(L)
      A(L,3)=C(L)
9600 CONTINUE
      N=100
      M=3
      NLL=100
      CALL PLOT (A,N,M,NLL)
      STOP
      END

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Fig. 3. Part three of the gradient calculation program.

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SUBROUTINE PLOT (A,N,M,NLL)
DIMENSION OUT(101),YPR(11),ANG(9),A(100,3)
1 FORMAT (1H1,50X26HDESIRED = 1, CALCULATED = 2//)
2 FORMAT (1X,F11.4,5X,101A1)
3 FORMAT (2X)
5 FORMAT (10A1)
7 FORMAT (16X,101H.
1
MY=5
MX=6
8 FORMAT (77,9X,11F10.4)
20 WRITE(MX,1)
READ(MY,5) BLANK,(ANG(I),I=1,9)
XSCAL=(A(N)-A(1))/ (FLOAT(NLL-1))
M1=N+1
M2=M+N
YMIN=A(M1)
YMAX=YMIN
DO 40 J=M1,M2
IF (A(J)-YMIN) 28,26,26
26 IF (A(J)-YMAX) 40,40,30
28 YMIN=A(J)
GO TO 40
30 YMAX=A(J)
40 CONTINUE
YSCAL=(YMAX-YMIN)/100.
XB=A(1)
L=1
MYX=M-1
I=1
45 F=I-J
XPR=XB+F*XSCAL
IF (A(L)-XPR) 50,50,70
50 DO 55 IX=1,101
55 OUT(IX)=BLANK
DO 60 J=1,MYX
LL=L+J*N
JP=((A(LL)-YMIN)/YSCAL)*1.
OUT(JP)=ANG(J)
60 CONTINUE
WRITE(MX,2) XPR,(OUT(IZ),IZ=1,101)
L=L+1
GO TO 80
70 WRITE(MX,3)
80 I=I+1
IF (I-NLL) 45,84,86
84 XPR=A(N)
GO TO 50
86 WRITE(MX,7)
YPR(1)=YMIN
DO 90 KN=1,9
90 YPR(KN+1)=YPR(KN)+YSCAL*10.
YPR(11)=YMAX
WRITE(MX,8) (YPR(IP),IP=1,11)
RETURN
END

```

Fig. 4. Program for graphic representation of the results of the calculation.

Results and discussion

A complete listing of the program and subroutines is given in Figs. 1-4. Fig. 5 shows the printed output and Fig. 6 demonstrates the graph that is obtained when the input consists of instructions to calculate a linear gradient. The results of the calculation are obviously correct. When a more complex gradient is specified the

TOLERANCE 1% 65 ITERATIONS

CHAMBER	MOLALITY	FRACTION	SPECIFIED	CALCULATED	PERCENT DEVIATION
1	.000	1	.0100	.0103	2.87
2	.1234	2	.0200	.0202	.86
3	.2468	3	.0300	.0301	.22
4	.3702	4	.0400	.0400	-.08
5	.5053	5	.0500	.0499	-.23
6	.6164	6	.0600	.0598	-.72
7	.7509	7	.0700	.0697	-.76
8	.8726	8	.0800	.0797	-.38
9	1.0039	9	.0900	.0896	-.39
		10	.1000	.0996	-.38
		11	.1100	.1096	-.37
		12	.1200	.1196	-.35
		13	.1300	.1296	-.33
		14	.1400	.1396	-.30
		15	.1500	.1496	-.27
		16	.1600	.1596	-.24
		17	.1700	.1696	-.21
		18	.1800	.1797	-.18
		19	.1900	.1897	-.15
		20	.2000	.1997	-.13
		21	.2100	.2094	-.10
		22	.2200	.2198	-.67
		23	.2300	.2299	-.35
		24	.2400	.2399	-.02
		25	.2500	.2500	-.00
		26	.2600	.2600	.02
		27	.2700	.2701	.03
		28	.2800	.2801	.05
		29	.2900	.2902	.05
		30	.3000	.3002	.06
		31	.3100	.3103	.09
		32	.3200	.3203	.09
		33	.3300	.3303	.10
		34	.3400	.3403	.10
		35	.3500	.3504	.10
		36	.3600	.3604	.10
		37	.3700	.3704	.10
		38	.3800	.3804	.10
		39	.3900	.3904	.09
		40	.4000	.4003	.08
		41	.4100	.4103	.08
		42	.4200	.4203	.07
		43	.4300	.4303	.06
		44	.4400	.4402	.06
		45	.4500	.4502	.04
		46	.4600	.4601	.02
		47	.4700	.4700	.01
		48	.4800	.4800	-.00
		49	.4900	.4899	-.02
		50	.5000	.4998	-.03
		51	.5100	.5098	-.05
		52	.5200	.5197	-.06
		53	.5300	.5296	-.08
		54	.5400	.5395	-.09
		55	.5500	.5494	-.10
		56	.5600	.5593	-.12
		57	.5700	.5691	-.13
		58	.5800	.5792	-.14
		59	.5900	.5891	-.15
		60	.6000	.5990	-.16
		61	.6100	.6090	-.17
		62	.6200	.6189	-.18
		63	.6300	.6288	-.18
		64	.6400	.6388	-.19
		65	.6500	.6487	-.19
		66	.6600	.6487	-.20
		67	.6700	.6487	-.20
		68	.6800	.6486	-.20
		69	.6900	.6484	-.20
		70	.7000	.6486	-.20
		71	.7100	.7084	-.19
		72	.7200	.7184	-.19
		73	.7300	.7287	-.18
		74	.7400	.7387	-.18
		75	.7500	.7487	-.17
		76	.7600	.7588	-.16
		77	.7700	.7689	-.15
		78	.7800	.7789	-.14
		79	.7900	.7890	-.13
		80	.8000	.7991	-.11
		81	.8100	.8092	-.10
		82	.8200	.8193	-.09
		83	.8300	.8294	-.07
		84	.8400	.8396	-.05
		85	.8500	.8497	-.03
		86	.8600	.8599	-.01
		87	.8700	.8701	.01
		88	.8800	.8802	.03
		89	.8900	.8904	.05
		90	.9000	.9006	.07
		91	.9100	.9109	.09
		92	.9200	.9211	.12
		93	.9300	.9313	.15
		94	.9400	.9416	.17
		95	.9500	.9519	.20
		96	.9600	.9621	.23
		97	.9700	.9726	.27
		98	.9800	.9830	.31
		99	.9900	.9934	.35
		100	1.0000	1.0039	.39

Fig. 5. Numerical output for a linear gradient input specification.

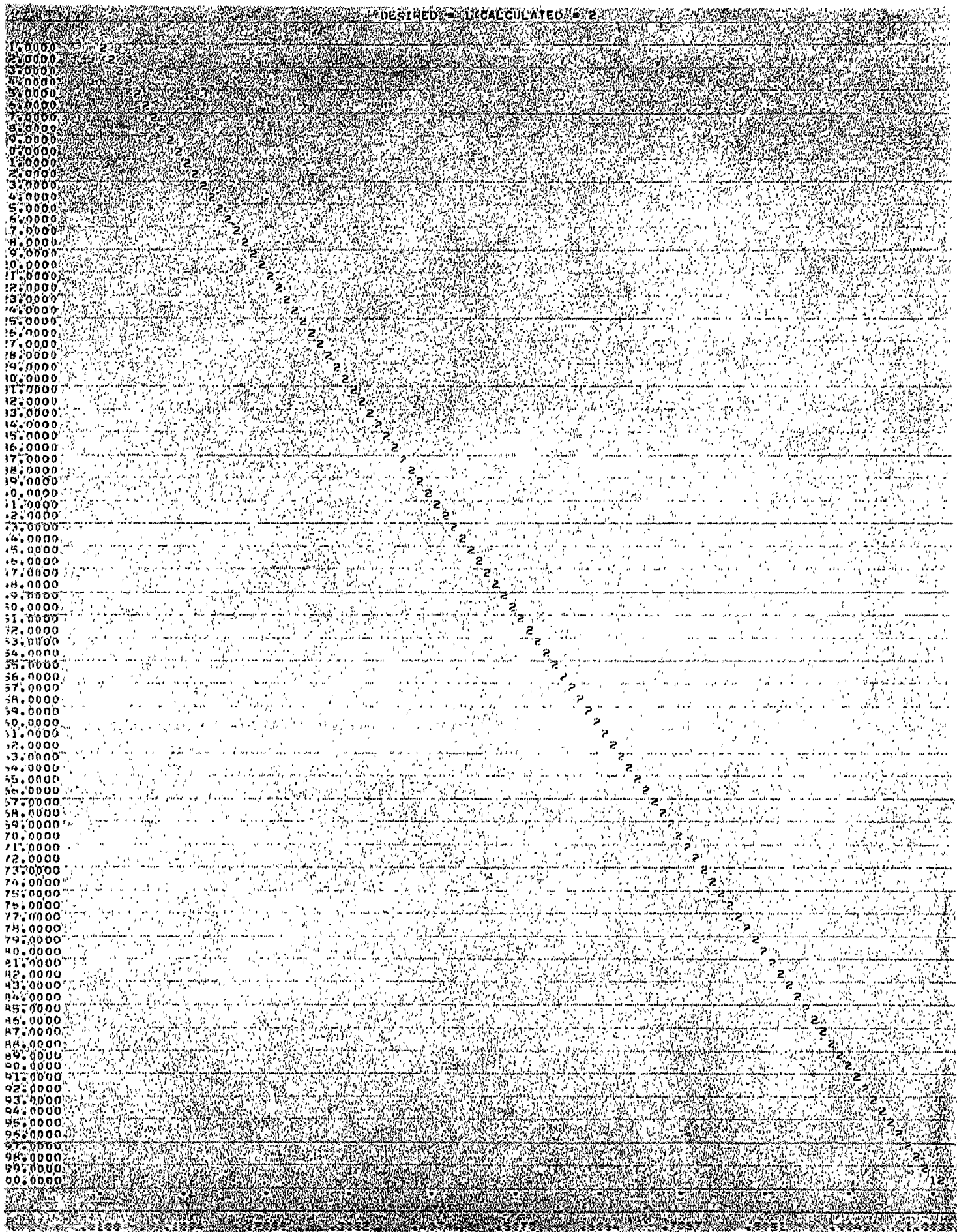


Fig. 6. Graphic representation for a linear gradient input specification.

DESIRED = 1, CALCULATED = 2

DESIRED	CALCULATED
1.0000	2
2.0000	2
3.0000	2
4.0000	2
5.0000	2
6.0000	2
7.0000	2
8.0000	2
9.0000	2
10.0000	2
11.0000	2
12.0000	2
13.0000	2
14.0000	2
15.0000	12
16.0000	12
17.0000	12
18.0000	12
19.0000	12
20.0000	12
21.0000	12
22.0000	12
23.0000	12
24.0000	2
25.0000	2
26.0000	2
27.0000	21
28.0000	21
29.0000	21
30.0000	21
31.0000	21
32.0000	21
33.0000	21
34.0000	21
35.0000	21
36.0000	21
37.0000	21
38.0000	21
39.0000	21
40.0000	21
41.0000	21
42.0000	21
43.0000	21
44.0000	21
45.0000	21
46.0000	21
47.0000	21
48.0000	21
49.0000	21
50.0000	21
51.0000	21
52.0000	21
53.0000	21
54.0000	21
55.0000	21
56.0000	12
57.0000	12
58.0000	12
59.0000	12
60.0000	12
61.0000	12
62.0000	12
63.0000	12
64.0000	12
65.0000	12
66.0000	12
67.0000	12
68.0000	12
69.0000	12
70.0000	12
71.0000	12
72.0000	12
73.0000	12
74.0000	12
75.0000	12
76.0000	12
77.0000	12
78.0000	21
79.0000	21
80.0000	21

satisfactory result shown in Fig. 7 is obtained. Fig. 8 gives the result obtained when the program is requested to calculate a very complex pattern (one which in fact would probably not be experimentally useful) but even in this case it is apparent that the calculation is possible. The utility of the program would appear to be great to those investigators engaged in the column chromatographic separation of complex mixtures.

At first glance it would appear that a least squares method of obtaining the solution to the simple simultaneous equations involved in the problem would be most efficient and satisfactory. Further consideration shows this assumption not to be the case since there is no simple way to avoid negative (and physically impossible) values as possible solutions to the system by the least squares method. The least squares solution is readily performed by machine computation, and it does in fact give negative values for all but the simplest gradients. Other mathematical techniques such as linear programming could undoubtedly be applied to this problem to obtain with certainty a "best fit", but these procedures seem unnecessarily sophisticated in the present instance. No simple proof that the results obtained by the method of approximation used are actually a "best fit" is apparent, but experience with the program with a variety of gradients in which the progress of the approximation process was observed numerically suggests that the results obtained are as good as can be obtained within the inherent physical restraints of the problem. Certainly they are within the experimental tolerance to be expected with all ordinary laboratory facilities for the formation of the gradients.

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